

AAT1102

Product information presented is current as of publication date. Details are subject to change without notice

# ADVANCED PWM DC-DC CONVERTER WITH INTERNAL SWITCH AND SOFT-START

#### **FEATURES**

• 1.6A, 0.23 $\Omega$ , Internal Switch

• High Efficiency: 90%

Adjustable Output: V<sub>DD</sub> to 12.5V

• Adjustable Frequency: 640kHz or 1.3MHz

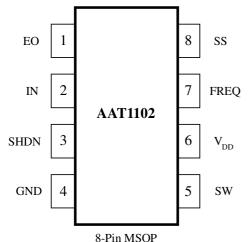
• Wide Input Range: +2.6V to +5.5V

Low Shutdown Current: 0.1μA

Programmable Soft-Start

Small 8-Pin MSOP Package

# PIN CONFIGURATION TOPVIEW



#### GENERAL DESCRIPTION

The AAT1102 is a step-up DC-DC converter with a 1.6A,  $0.23\Omega$  internal switch. Equipped with an external compensation pin, this device offers user flexibility in determining loop dynamic and adjusting operating frequency. AAT1102 also allows the use of small, low equivalent resistance (ESR) ceramic output capacitor, and it's capable of converting a standard input of 3.3V to multiple outputs of 8V, -8V, and 23V. Furthermore, filtering and loop performance are facilitated and enhanced by a high switching frequency of either 640 kHz or 1.3 MHz.

The AAT1102's versatility comes with a power-smart design. A soft-start programmed with an external capacitor that sets the input current ramp rate, reduces the current consumption to  $0.1\mu A$  in shutdown mode. When operating, a mere 2.6V input yields an impressive output voltage as high as 12.5V.

High switching frequency and economical design allow AAT1102 to be less than 1.1mm high. Its compact 8-pin MSOP package and superior performance make it an ideal part for biasing TFT displays.

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### PIN DESCRIPTIONS

PIN	NAME	FUNCTION
1	EO	Compensation Pin for Error Amplifier
2	IN	Feedback Pin with a Typical Reference Voltage of 1.24V, $V_{OUT} = IN(1 + \frac{R1}{R2})$
neet4U.com	SHDN	Shutdown Control Pin. The Device Will Turn Off When SHDN is Low
4	GND	Ground
5	SW	Switch Pin
6	$V_{_{ m DD}}$	Power Supply Pin
7	FREQ	Frequency Select Pin. Switch Oscillator Frequency to 640kHz When FREQ is Low, and 1.3MHz When FREQ is High
8	SS	Soft-Start Control Pin. No Soft-Start When the Pin is Left Open

### ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	VALUE	UNIT
SW to GND		-0.3 to $+18$	V
IN, SHDN, $V_{DD}$ , FREQ to GND		-0.3 to +6	V
SS, EO to GND		$-0.3 \mathrm{V} \text{ to } (\mathrm{V}_{\mathrm{DD}} + 0.3 \mathrm{V})$	V
RMS SW Pin Current	$I_{sw}$	1.2	A
Continuous Power Dissipation $(T_C = +70 \degree C)$ 8-Pin MSOP (De-Rate $4.1 \text{ mW } / ^{\circ}C$ above $+70 \degree C$ )	$P_d$	330	mW
Operation Temperature Range	${ m T_{C}}$	-20 to $+85$	$^{\circ}\! {\mathbb C}$
Storage Temperature Range	$T_{\text{storage}}$	-45 to +125	$^{\circ}\! \mathbb{C}$
Lead Temperature (Soldering for 10 seconds)	$T_{\scriptscriptstyle L}$	+300	$^{\circ}\! C$

#### Note:

- 1. Absolute Maximum Ratings are threshold limit values that must not be exceeded.
- 2. Operation above these absolute maximum ratings may cause degradation or permanent damage to the device.
- 3. These are stress ratings only and do not necessarily imply functional operation below these limits.

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### **ELECTRICAL CHARACTERISTICS**

 $V_{\rm DD} = \overline{SHDN} = 3V$ , FREQ = GND, unless otherwise specified. Typical values are at  $T_{\rm C} = +25^{\circ}C$ )

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Supply Voltage Range	$V_{_{ m DD}}$		2.6		5.5	V
V <sub>DD</sub> Under Voltage Lockout		When $V_{DD}$ is rising, typical hysteresis is 40mV; SW remains off below this level		2.38	2.52	V
Quiescent Current	$I_{ m DD}$	$V_{IN} = 1.3V$ , not switching		0.21	0.35	mA
Quiescent Current	¹DD	$V_{IN} = 1.0V$ , switching		1.2	5.0	ША
Shutdown Current	$I_{sc}$	$\overline{SHDN} = GND$		0.1	10.0	μΑ

#### **ERROR AMPLIFIER**

STREET STREET						
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Feedback Voltage	V <sub>IN</sub>	Level to produce $V_{EO} = 1.24V$	1.222	1.240	1.258	V
V <sub>DD</sub> Input Bias Current	$I_{IN}$	$V_{IN} = 1.24V$		0	40	nA
Feedback-Voltage Line Regulation		Level to produce $V_{EO} = 1.24V$ , $2.6V < V_{DD} < 5.5V$		0.05	0.15	%/V
Transconductance	g <sub>m</sub>	$\Delta I = 5 \mu A$	70	105	240	μA /V
Voltage Gain	$A_{V}$			1,500		V/V

### **OSCILLATOR**

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Frequency	l fora	FREQ = GND	540	640	740	1.77	
		$FREQ = V_{DD}$	1,100	1,320	1,600	kHz	
M ' D ( C 1	l l)	FREQ = GND	79	85	92	07	
Maximum Duty Cycle		$FREQ = V_{DD}$		85		%	

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### **ELECTRICAL CHARACTERISTICS**

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### **N-CHANNEL SWITCH**

PARAMETER SYMBOL		CONDITIONS	MIN	TYP	MAX	UNITS
Current Limit	$I_{LIM}$	$V_{DD}$ = 1V, Duty Cycle = 65%	1.2	1.6	2.3	A
On-Resistance	R <sub>ON</sub>	$I_{SW} = 1.2A$		0.23	0.50	Ω
Leakage Current	$I_{\text{SWOFF}}$	$V_{SW} = 12V$		0.01	20.00	μΑ

### **SOFT-START**

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Reset Switch Resistance					300	Ω
Charge Current		$V_{SS} = 1.2V$	1.5	4.0	7.0	μΑ

### **CONTROL INPUTS**

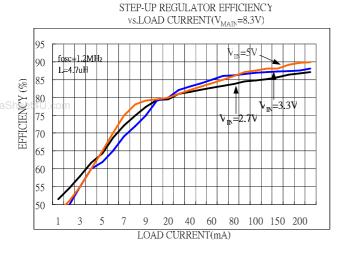
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Input Low Voltage	V	SHDN, FREQ; $V_{DD} = 2.6V$			0.3	V	
mp or zero verage	· IL	to 5.5V			$ m V_{DD}$	·	
Input High Voltage	V	SHDN, FREQ; $V_{DD} = 2.6V$				V	
input riigii voitage	$V_{_{ m IH}}$	to 5.5V	$ m V_{DD}$			v	
Hystorasis		SHDN, FREQ		0.1		V	
Hysteresis		SHDN, FREQ		$ m V_{_{DD}}$		v	
FREQ Pull-Down Current	$I_{FREQ}$		1.8	5.0	9.0	μΑ	
SHDN Input Current	I			0.001	1.000	μΑ	

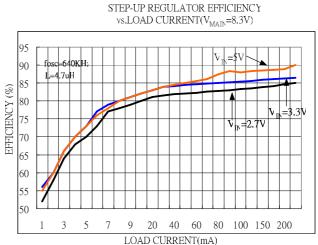
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### **Typical Operating Characteristics**





8.4

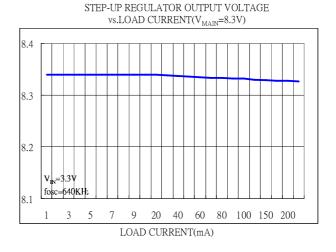
8.2

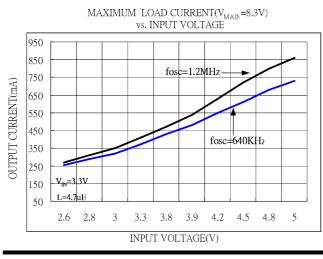
V<sub>IN</sub>=3.3V

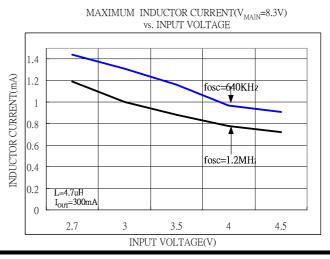
fpsc=1.2MHz

1 3 5 7 9 20 40 60 80 100 150 200

LOAD CURRENT(MA)





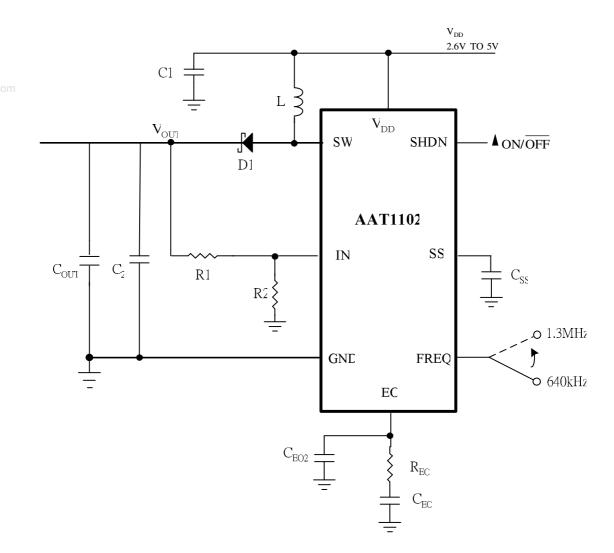


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### Fig. 1 TYPICAL APPLICATION CIRCUIT

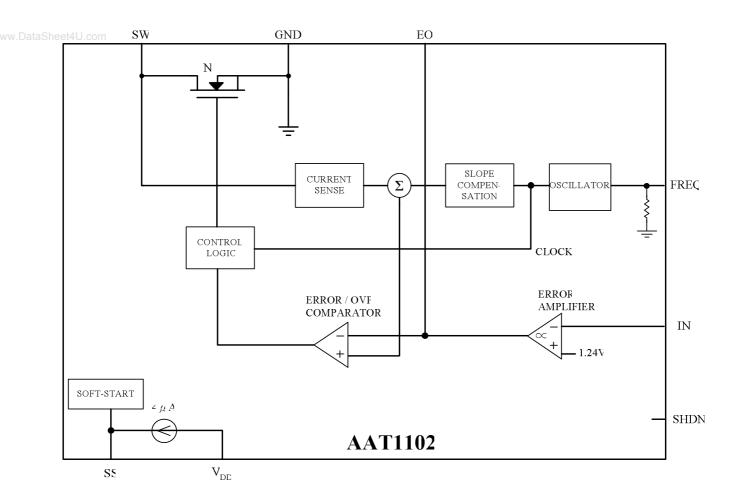


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Fig. 2 BLOCK DIAGRAM



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Fig. 3 AAT1102 IN A SEPIC CONFIGURATION

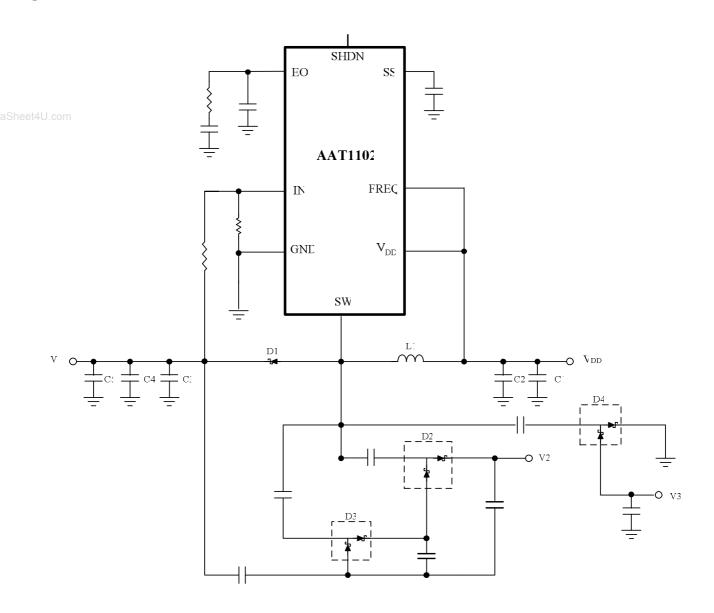
 $\begin{array}{c} V_{DD} \\ 2.6V \text{ TO 5V} \\ \end{array}$ 

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Fig. 4 MULTIPLE-OUTPUT TFT LCD POWER SUPPLY



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### **Inductor selection**

$$I_{L(peak)} = I_{IN} + \frac{V_{IN}D}{2Lf_s}$$
, where  $D$  is duty cycle

And 
$$I_{IN} = \frac{I_o}{1 - D}$$
,  $D = 1 - \frac{V_{IN}}{V_o}$ ,

The inductor current rating must be greater than  $I_{L(peak)}^{\text{et4U.com}}$ 

### **Loop Compensation Design**

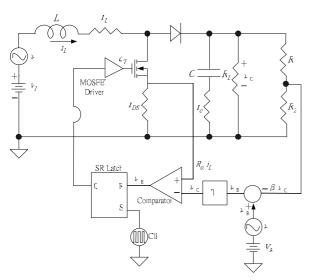


Fig.1. Closed-current loop for boost with PCM

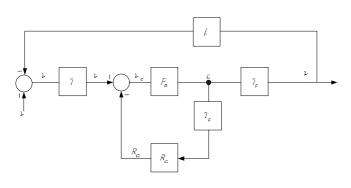


Fig.2. Block diagram of boost converter with PCM

### **Power Stage Transfer Functions**

The duty to output voltage transfer function  $T_p$  is:

$$T_p(s) = \frac{v_o}{d} = T_{p0} \frac{(s + w_{esr})(s - w_{z2})}{s^2 + 2\xi w_n s + w_n^2}$$

Where 
$$T_{p0} = V_O \frac{-r_c}{(1-D)(R_L + r_c)}$$
,  $w_{esr} = \frac{1}{Cr_c}$ 

And

$$\begin{split} w_{z2} &= \frac{R_L (1-D)^2 - r}{L}, w_n = \sqrt{\frac{(1-D)^2 R_L + r}{LC(R_L + r_c)}} \\ \xi &= \frac{C[r(R_L + r_c) + R_L r_c (1-D)^2] + L}{2\sqrt{LC(R_L + r_c)}[r + (1-D)^2 R_L]} \,, \end{split}$$

$$r = r_L + Dr_{DS} + (1 - D)R_F$$

 $r_L$  is the inductor equivalent series resistance,  $r_c$  is capacitor ESR,  $R_L$  is the converter load resistance, C is output filter capacitor,  $r_{DS}$  is the transistor on-resistance, and  $R_F$  is the diode forward resistance.

The duty to inductor current transfer function  $T_{pi}$  is:

$$T_{pi}(s) = \frac{i_l}{d} = T_{pi0} \frac{s + w_{zi}}{s^2 + 2\xi w_n s + w_n^2}$$

Where 
$$T_{pi0} = \frac{V_O(R_L + 2r_c)}{L(R_L + r_c)}$$
,  $w_{zi} = \frac{1}{C(R_L / 2 + r_c)}$ 

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### **Current Sampling Transfer Function**

Error voltage to duty transfer function  $F_m$  is:

$$F_m(s) = \frac{d}{v_{ei}} = \frac{2f_s^2(s^2 + 2\xi w_n s + w_n^2)}{T_{pi0}R_{cs}s(s + w_{zi})(s + w_{sh})}$$

Where 
$$w_{sh} = \frac{3w_s}{\pi} \left( \frac{1-\alpha}{1+\alpha} \right), \alpha = \frac{M_2 - M_a}{M_1 + M_a}$$

$$w_s = 2\pi f_s$$

Therefore,  $F_m$  depends on duty to inductor current  $T_c(s) = \frac{v_c}{v_a} = g_m R_c \frac{s + w_c}{s}$ , where  $w_c = \frac{1}{R_c C_c}$ transfer function  $T_{pi}$ , and  $f_s$  is the clock switching frequency;  $R_{cs}$  is the current-sense amplifier transresistance. For the boost converter  $M_1 = V_{IN}/L$ and  $M_2 = (V_O - V_{IN})/L$ 

For AAT1102,  $R_{cs} = 0.275 \text{ V/A}$ ,  $M_a$  is slope compensation,  $M_a = 0.8 \times 10^{6}$ .

The closed-current loop transfer function  $T_{icl}$ 

$$T_{icl}(s) = \frac{12f_s^2}{R_{cs}T_{pi0}} \times \frac{\left(s^2 + 2\xi w_n s + w_n^2\right)}{\left(s + w_{zi}\right)\left(s^2 + w_{sh} s + 12f_s^2\right)}$$

### The Voltage-Loop Gain With **Current Loop Closed**

The control to output voltage transfer function  $T_d$ 

$$T_d(s) = \frac{v_o(s)}{v_c(s)} = T_{icl}(s)T_p(s)$$

The voltage-loop gain with current loop closed is:

$$L_{vi}(s) = \beta T_c(s) T_d(s)$$

$$= \beta g_{m} R_{c} \frac{s + w_{c}}{s} \frac{12 f_{s}^{2} T_{p0}}{R_{cs} T_{pi0}} \times \frac{(s + w_{z1})(s - w_{z2})}{(s + w_{zi})(s^{2} + sw_{sh} + 12 f_{s}^{2})}$$
Where  $\beta = \frac{V_{FB}}{V_{O}}$ ,

The compensator transfer function

$$T_c(s) = \frac{v_c}{v_{fb}} = g_m R_c \frac{s + w_c}{s}$$
, where  $w_c = \frac{1}{R_c C_c}$ 

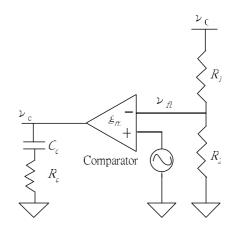


Fig.3. Voltage loop compensator

Compensator design guide:

- 1. Crossover frequency  $f_{ci} < \frac{1}{2} f_s$
- 2. Gain margin>10dB
- 3. Phase margin>40°
- 4. The  $|L_{vi}(s)| = 1$  at crossover frequency, Therefore, the compensator resistance,  $R_c$  is determined by:



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$$R_{c} = \frac{V_{o}}{V_{FB}} \frac{2\pi f_{ci} C R_{cs}}{k g_{m}} \frac{(R_{L} + 2r_{c})}{\left[ (1 - D)R_{L} - \frac{r}{(1 - D)} \right]}$$

 $V_{FB}$  is equal to reference voltage,  $V_{REF}$ .  $V_{REF} = 1.24$ V, k is the correct factor, and k = (6 - 8)

5. The output filter capacitor is chosen so C.  $R_L$  pole cancels  $R_c$ .  $C_c$  zero

$$R_c C_c = \frac{C}{(1-3)} \left( \frac{R_L}{2} + r_c \right)$$
, and 
$$C_c = \frac{C}{(1-3)R_c} \left( \frac{R_L}{2} + r_c \right)$$

#### Example:

 $V_{IN}$  =5V,  $V_{O}$  =9.6V,  $I_{O}$  =250mA,  $f_{s}$  =600 kHz,  $V_{FB}$  =1.25V, L = 6.8uH ,  $g_{m}$  = 105uS ,  $R_{cs}$  = 0.275 V/A,  $r_{L}$  = 0.1 $\Omega$  ,  $r_{DS}$  = 0.23 $\Omega$  ,  $r_{c}$  = 50m $\Omega$  , k =7  $R_{F}$  = 1.4 $\Omega$  ,  $f_{ci}$  = 21.4 kHz,  $C_{c}$  =1.3nF,  $R_{c}$  = 27k  $\Omega$  , C =4.7uF

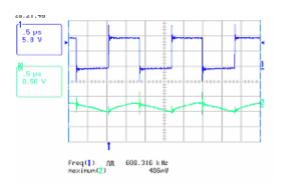


Fig.4. CH1: PWM waveform, CH2,  $v_{p-p}$  for Vo

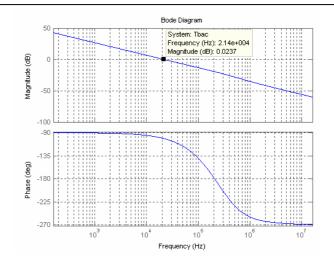
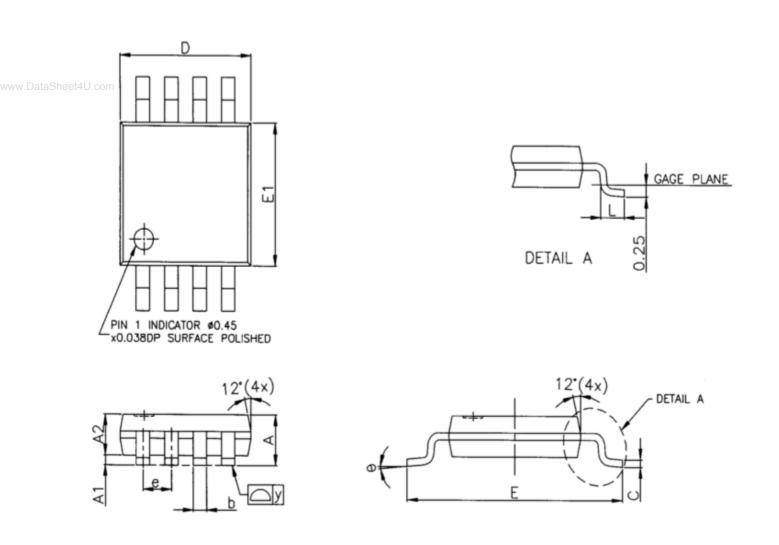


Fig.5. Bode diagram using Matlab simulation



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# PACKAGE DIMENSION MSOP-8



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### PACKAGE DIMENSION (CONT.) MSOP-8

Γ,	SVALDOLIC	DIMENSIONS IN MILLIMETERS			DIMENSIONS IN INCHES			
1	SYMBOLS	MIN	NOM	MAX	MIN	NOM	MAX	
	Α	0.81	1.02	1.22	0.032	0.040	0.043	
n 🛭	M-UAdom_	0.05	_	0.15	0.002		0.006	
L	A2	0.76	0.86	0.97	0.030	0.034	0.038	
L	b	0.28	0.30	0.38	0.011	0.012	0.015	
L	С	0.13	0.15	0.23	0.005	0.006	0.009	
	D	2.90	3.00	3.10	0.114	0.118	0.122	
	Ε	4.80	4.90	5.00	0.189	0.193	0.197	
	E1	2.90	3.00	3.10	0.114	0.118	0.122	
	е	_	0.65	_	_	0.0256	_	
L	L	0.40	0.53	0.66	0.016	0.021	0.026	
	у		_	0.076		_	0.003	
	0	0,	3'	6.	0,	3*	6*	
$\perp$								

#### NOTE:

- 1. CONTROLLING DIMENSION: mm
- 2. LEAD FRAME MATERIAL : OLIN C7025
- 3. DIMENSION "D" DOES NOT INCLUDE MOLD FLASH, TIE BAR BURRS AND GATE BURRS. MOLD FLASH, TIE BAR BURRS AND GATE BURRS SHALL NOT EXCEED 0.006"[0.15mm]
  PER END. DIMENSION "E1" DOES NOT INCLUDE INTERLEAD FLASH. INTERLEAD FLASH SHALL NOT EXCEED 0.010"[0.25mm] PER SIDE.
  4. DIMENSION "b" DOES NOT INCLUDE DAMBAR
- PROTRUSION. ALLOWABLE DAMBAR PROTUSION SHALL BE 0.003"[0.08mm] TOTAL IN EXCEED OF THE "b" DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND AN ADJACENT LEAD TO BE 0.0028"[0.07mm].

  5. TOLERANCE: ±0.010"[0.25mm] UNLESS
- OTHERWISE SPECIFIED.

  6. OTHERWISE DIMENSION FOLLOW ACCEPTABLE SPEC.

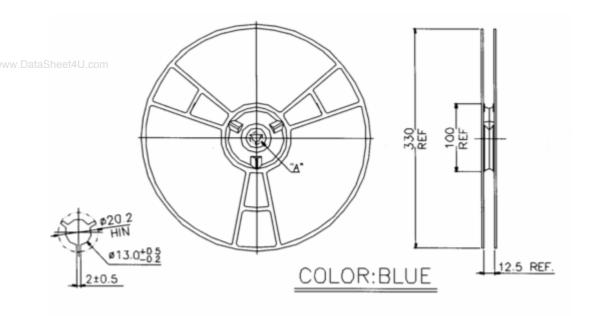
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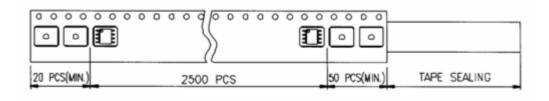


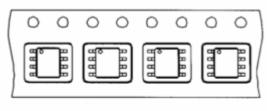
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### TAPE AND REEL

PACKING METHOD: 2,500PCS/REEL, 1 REEL/BOX







MSOP 8L

包装方式: 2500 EA/PER REEL 1 REEL/BOX

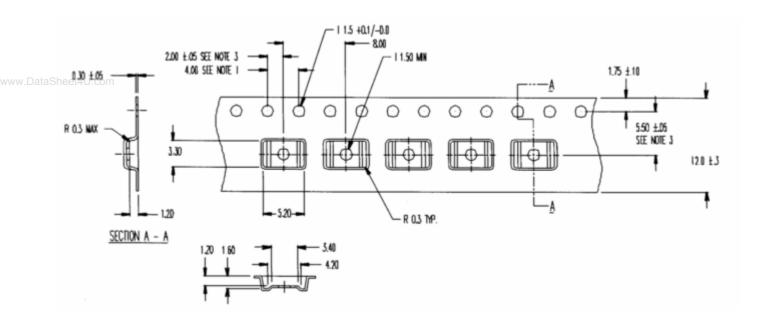
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TAPE AND REEL (CONT.)

PACKING METHOD: 2,500PCS/REEL, 1 REEL/BOX



### NOTES:

- 1. 10 SPROCKET HOLE PITCH CUMULATIVE TOLERANCE ±0.2
- 2. CAMBER IN COMPLIANCE WITH EIA 481
- POCKET POSITION RELATIVE TO SPROCKET HOLE MEASURED AS TRUE POSITION OF POCKET, NOT POCKET HOLE

X.XXXX ±0.006 X.XXX ±0.025 X.XX ±0.10 X. ±0.25 Note: the contraction of the contraction o

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### **PART MARKING**

### **MSOP8 TOP MARKING**

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**MSOP8 BACK MARKING** 

YYWW

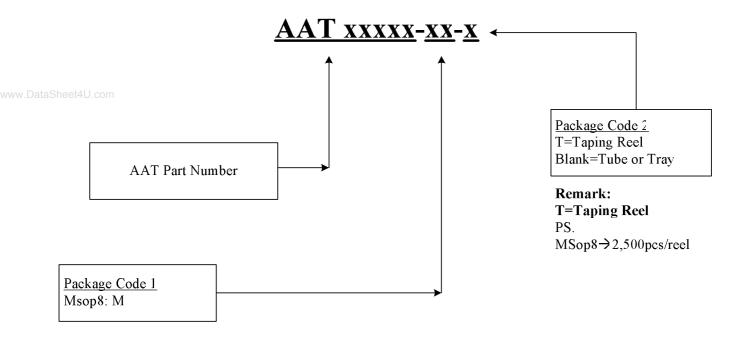
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